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VLF sensors for lightning research

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Abstract

The lightning localization task is very interested for the meteorologist organizations, airlines, networks operators, military and etc. The electromagnetic properties of lightning can be measured using VLF sensor. The paper deals with some hardware and software of VLF sensors used in IKIR FEB RAS.

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1. VLF sensor hardware

During the development of remote methods for investigation of magnetosphere dynamics, synoptic weather systems, detection of volcano explosive eruptions, we applied peculiarities of radio signal propagation. Radio pulses of lightning discharges (atmospherics). Radio pulses of lightning discharges, propagation along the Earth surface via the Earth-ionosphere waveguide, carry information on synoptic weather system structure, repeating by its intensity and spatial distribution the structure of cloud formations. The radio pulses, penetrating into magnetospheric waveguides, receive a characteristic form (whistler) and carry information on weather system state in the magnetosphere. Volcano explosive eruptions may also be accompanied by lightning discharges which may be applied to detect volcanic eruptions in the conditions of dense cloudiness [1].

In general, the Very Low Frequency (VLF) sensor consists of a receiving part and a data acquisition module. The reception part consists of: antenna (see Fig. 1a), amplifiers, filters. Data acquisition module consists of: analog-todigital converter (ADC), digital recorder, time synchronization module, etc. As an integral component of the various types of VLF sensors considered the use of mini-computers, audio and video cards, specialized ADC, various types of antennas (Fig. 1b). Preamplifier (used in IKIR FEB RAS) for the vertical electric antenna is made for each station separately. Principle circuit is shown in Fig. 1c. Preamplifier (PA) consists of two cascades. The first one is built on a operational amplifier DA1, and it is a noninverting voltage amplifier with the gain of 11. The second cascade is an integrated buffer amplifier with differential output. The microcircuit DA3 serves to generate a midpoint of supply voltage as long as the scheme requires balanced ambipolar feed. The microcircuit DA1 – AD744 or any other with the performance of not less than 50 volt/mcs, analogous layout of outputs and supply voltage. The microcircuit DA2 – SSM2142 does not have analogs and irreplaceble. Diods VD1 and VD2 by IN4148 or analogous. Metal-oxide resistors with the power of 0,125 W. Condensators C2, C3, C7, C9, C14, C15 are polar, tantalum of K53-13 type, meant for the voltage of not less than 16 V or analogous hermetical with operating temperature of -30°C...+80°C. There is also an opportunity to install SMD condensators with similar parameters in «A» type casing. Printed circuit board is shown in Fig. 2a.



Fig. 1. (a) some types of antennas used in IKIR for whistler detection and lightning localization; (b) an example of VLF sensor components; (c) principle circuit of the preamplifier.

The preamplifier is fed from the AC adapter with the constant voltage from 25 to 30 V. The PA is in a metal casing and can be used outside all year round. The PA is installed in the immediate proximity to an antenna. For power supply and signal transmission from the PA, UTP5 cable (four screened twisted pairs) is laid outside. One pair in each arm is used for power supply, one twisted pair is used for signal transmission and one of them is not used. We mount the PA near the antenna, we may say that it is a part of antenna construction. An example of a prepared PA mounted on the antenna is shown in Fig. 2b. After installation, the PA does not require adjustment and is ready to be operated if properly mounted.

As long as antennas are not standardized device, the level of the signal on each of them will be different. The gain of the first cascade may be altered by changing the nominal of R2 and R4 resistors within some limits. There are no strict requirements to the level of output signal. It is important that the level of «powerful» atmospherics does not exceed the maximum input voltage of the digitizing device. In our case, it is a sound card.



Fig. 2. (a) printed circuit board of the preamplifier; (b) an example of a prepared PA mounted on the antenna.

A flagpole vertical antenna is used to record VLF signals. Such antennas have a large number of different constructions manufactured industrially and handmade without large financial expenditures. The latter criterion is very important since the low cost of a lightning sensor system is of great priority in the development of the whole complex. For example, a ship receiving antenna is applied at Paratunka and Karymshina Geophysical Observatories of IKIR FEB RAS. Such a solution provides good signal reception but the cost and complexity of installation do not correspond to «Lightning sensor system» project. That is why, some works were carried out to build antennas from available materials which characteristics satisfied the requirements for VLF signal registration in the defined range (not more than 100 kHz).

First of all, we studied the way of antenna construction by WWLLN [2] specialists. This method is very simple and may be applied in living environment from available materials. Antenna is a wire put into a plastic tube of a small diameter (15-20 mm depending on the wire thickness). The wire forms a loop on the top. Different kinds of wires, solid and stranded, may be applied. For example a usual wire for local communication networks UTP5, four twisted pairs without a screen, were used in an antenna at a WWLLN station in Singapore.

The antenna may be also constructed form a simple plastic tube for hot water. Such antenna was constructed at a WWLLN station at Khabarovsk Geophysical Observatory of IKIR FEB RAS. The walls of such tubes are reinforced with metal, in particular with aluminum alloys. That means there is a metal cylinder inside a tube. It may be used as an antenna. By the way, there is a number of industrial solutions where antenna is made of a metal cylinder. Such an antenna is installed at a WWLLN station at Magadan Geophysical Observatory of IKIR FEB RAS.

Antenna is mounted on the roof of a building of a station as high as possible. The length of an antenna is chosen according to the conditions of installation and operation (constructive peculiarities of a building, weather conditions etc.) but not less than 3 meters since its efficiency depends on the length.

To reveal the effects caused by seismic activity, atmospherics have been measured in the wintertime in Yakutsk, using a onepoint lightning location system with increased sensitivity in order to increase the range of operation as compared to the summer period [3]. The lightning discharge direction is found using three antennas that receive the vertical electric and two horizontal magnetic components of the electromagnetic field. The direction toward lightning discharges is deter mined relative to the rms signal values coming from the magnetic antennas. The direction determination ambiguity is eliminated by comparing the signs of mutual correlation between the signal electric and magnetic components of an atmospheric. The maximal standard error in direction determination is $\sim 2.5^{\circ}$. The temporal signal waveform, i.e., the number of positive and negative halfperiods of the electric component exceeding the level equal to 0.1 of the signal maximal value, is used to roughly estimate the distance to a remote lightning discharge. The range coefficient is determined by converting the summer threshold values into the winter ones and is specified by comparing these values with the data of the satellite system for registering lightning discharges (LIS) and the WWLLN worldwide ground based network.

2. VLF sensor software

One imposes on a VLF sensor the following basic tasks: saving received data on remote server; detecting PPSimpulses with given precision; time synchronization of received data; stream identification and classification by various parameters of atmospherics, whistlers, anomalies in received data; etc.





For time synchronization, one uses a GPS-receiver which, once a second, generates PPS-impulses as shown in Fig. 3 and 4. For stream identification, one implements their cubic spline interpolation with given precision at a mini-computer (Fig. 4 and considers both ascending and descending fronts of a PPS-impulse. Such approach allows

to assure the precision of $\sim 8,12 \times 10^{-8}$ sec for definining the middle of a PPS-impulse ascending front, when using a sound card ASUS Xonar U5 with frequency discretization 192 kHz.



Fig. 4. an example of a cubic spline interpolation of a PPS-impulse ascending front.

As PPS-impulses are being identified in stream mode on a mini-computer of the VLF sensor, it is not rational to store the particular PPS-channel at a remote server. Instead, one saves the meta-information of time synchronization into a file (Fig. 5). Each line of the example provided in Fig. 5 contains 16 fields separated by TAB symbol. The first field stores the sample number (double value) of the timestamp which value written in the second field. The third field stores the number of a sample, starting with which the rest of the line contains 13 digitalized by a sound card values of a PPS-impulse.

An example of a spectrogram of a signal received with help of a VLF sensor with a vertical electrical antenna is provided in Fig. 6.

140446 2629349788	13:25:34	140440:	27448	-28318	46988	- 56488	94253	-159941	661782	2558752	2388321	2481661	2425420	2458828	2438928
332444,7241350533	13:25:35	332438:	2296	8221	-5142	20145	-24472	52241	-80552	1846379	2597779	2362831	2503366	2405227	2476468
524443,2173823696	13:25:36	524437:	28103	-29984	49319	-61281	100837	-176201	763422	2583435	2374161	2498944	2419855	2463683	2435679
716441,6779141850	13:25:37	716435:	6244	4135	765	12268	-12493	33771	-32860	1950030	2576682	2374304	2496660	2409641	2474292
908440,1688215185	13:25:38	908434:	29090	-29701	51329	-63858	107086	-188091	868229	2608763	2362935	2498460	2413347	2468633	2431573
1100438,6338731959	13:25:39	1100432:	8225	-664	6281	3562	-824	14249	18199	2040044	2555998	2385004	2498869	2414012	2471292
1292437,1155901547	13:25:40	1292431:	30062	-28193	53921	-62738	113266	-195870	986225	2629597	2352316	2505600	2408101	2472130	2429042
1484435,5868127240	13:25:41	1484429:	12931	-2415	14733	-1269	14422	-3811	77448	2125768	2534227	2397248	2482683	2419715	2467795
1676434,0607155608	13:25:42	1676428:	26701	-30379	50378	-65852	111648	-202870	1092935	2641397	2345466	2509013	2404293	2474876	2425941
1868432,5387992319	13:25:43	1868426:	14040	-9565	17427	-13290	23296	-29114	137766	2202635	2511696	2408540	2474511	2423969	2463857

Fig. 5. an example of the meta-information of time synchronization.



Fig. 6. an example of a spectrogram of a signal received with a vertical electrical antenna.

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